

Extension 5

9/22/09

QFT II

Note Title

9/22/2009

Practical Group Theory

SU(N) groups - $N \times N$ unitary, $\det U = 1$

$$U = e^{iH} \quad H \text{ hermitian}$$

$$\det U = e^{\text{Tr} \ln U} = e^{i \text{Tr} H} \quad \Rightarrow H \text{ is traceless}$$

Parameters	$N \times N$ Hermitian	N^2
	Traceless	$N^2 - 1$
	Diagonal	$N - 1$

Invariance of 2 objects

$$\psi = \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \rightarrow \psi \rightarrow \psi' = U \psi \quad U^\dagger U = 1$$

$$\psi^\dagger \psi \rightarrow \psi'^\dagger \psi' = \psi^\dagger \psi$$

Unitary 2×2

$$U = e^{-i(\alpha \mathbb{1} + \vec{\alpha} \cdot \vec{\tau})}$$

\uparrow $U(1)$ \uparrow $SU(2)$

$\tau^i =$ Pauli matrices (σ^i)

$$[\tau^i, \tau^j] = 2i \epsilon^{ijk} \tau^k$$

$$\text{Tr}(\tau^i \tau^j) = 2 \delta^{ij}$$

$$\tau^i \tau^j = \mathbb{1} \delta_{ij} + i \epsilon^{ijk} \tau^k$$

$$(\tilde{\tau}^i)_{ab} (\tilde{\tau}^i)_{cd} = 2 \left(\delta_{ad} \delta_{bc} - \frac{1}{2} \delta_{ab} \delta_{cd} \right)$$

Checks

$$\delta^{ab} (\tilde{\tau}^a)_{ab} (\tilde{\tau}^a)_{cd} = 2 \left(\delta_{cd} - \frac{1}{2} \times 2 \delta_{cd} \right) = 0$$

$$(\tilde{\tau}^i)_{ab} (\tilde{\tau}^i)_{ba} = \text{Tr}(\tilde{\tau}^i \tilde{\tau}^i) = 6 = 2 \left(2 \times 2 - \frac{1}{2} \times 2 \right) = 6 \quad \checkmark$$

$$(\tilde{\tau}^j)_{ab} \tilde{\tau}^i_{ab} \tilde{\tau}^i_{cd} = 2 \delta_{ij} \tilde{\tau}^i_{cd} = 2 \tilde{\tau}^j_{cd} = 2 \gamma^j_{cd}$$

Invariants $\bar{\Psi} \not{\partial} \Psi \rightarrow \bar{\Psi} U^\dagger \not{\partial} U \Psi$
 $\bar{\Psi} \not{\partial} \Psi$

if $\not{\partial} \propto \mathbb{1}$
 $\tau_{2 \times 2}$

What about

$\bar{\Psi} \tau^i \Psi \rightarrow \bar{\Psi} \underbrace{U^\dagger \tau^i U}_{2 \times 2, \text{ Hermitian, Traceless}} \Psi$

$2 \times 2, \text{ Hermitian, Traceless} \Rightarrow R_{ij} \tau^i \tau^j$

Find

$\leftarrow U = e^{-i\alpha \cdot \vec{\tau}}$

$R^{ij} = \frac{1}{2} \text{Tr}(R_{ik} \tau^k \tau^j) = R^{ij} = \frac{1}{2} \text{Tr}(U^\dagger \tau^i U \tau^j)$

Claim $R^{ij} = \text{Orthogonal } 3 \times 3 \text{ matrix } \mathcal{O}(3)$

$R^{ij} R^{kj} = \delta^{ik} = \frac{1}{2} \text{Tr}(\underbrace{U^\dagger \tau^i U}_{(U^\dagger \tau^i U)_{ba}} \tau^j) \frac{1}{2} \text{Tr}(\underbrace{U^\dagger \tau^k U}_{(U^\dagger \tau^k U)_{dc}} \tau^j)$

$= \frac{1}{4} \int d^3x \left[(U^\dagger \tau^i U)_{ba} (U^\dagger \tau^k U)_{cb} - \frac{1}{2} (U^\dagger \tau^i U)_{ab} \delta^{ab} (U^\dagger \tau^k U)_{dc} \delta^{cd} \right]$

$$= \frac{1}{2} \times \text{Tr}(u^\dagger \tau^i u u^\dagger \tau^k u) = \delta^{ik} \quad \checkmark$$

$\Rightarrow \mathcal{O}(3)$ vector $V_i \rightarrow R_{ij} V_j$

$$u = e^{-i\alpha \tau_z}$$

$$\Rightarrow R_{ij} = \begin{pmatrix} \cos 2\alpha & \sin 2\alpha & 0 \\ -\sin 2\alpha & \cos 2\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \Theta = 2\alpha$$

Two fold mapping $SU(2) \rightarrow \mathcal{O}(3)$ $\alpha = \pi$ $R_{ij} = 1$
 $\alpha = 2\pi$ $R_{ij} = 1$

$SU(2)$ Representations

doublet $\psi = \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}$ $\psi \rightarrow U\psi$ "fundamental"

vector $\pi^i = (\pi^1, \pi^2, \pi^3) \rightarrow R^{ij} \pi^j$ "adjoint"

$\bar{\psi}\psi$ singlet

$\bar{\psi} \tau^i \psi$ vector

$$2 \otimes 2 = 1 \oplus 3$$

$$\frac{1}{2} \otimes \frac{1}{2} = 0 \oplus 1 \quad \leftarrow \text{"spin"}$$

Invariants

$$L = \bar{\Psi} \tau^i \Psi \Pi^i \longrightarrow R^{ij} \bar{\Psi} \tau^j \Psi R^{ik} \Pi^k = \bar{\Psi} \tau^i \Psi \Pi^i$$

$\underbrace{\hspace{10em}}_{\delta^{jk}}$

Matrix notation:

$$\Pi = \tau^i \Pi^i \quad 2 \times 2 \text{ matrix}$$

Transform

$$\Pi \rightarrow \tau^i R^{ij} \Pi^j = \frac{1}{2} \tau^i \text{Tr}(U^\dagger \tau^i U \tau^i) \Pi^j$$

$\uparrow_{ab} \quad (\tau^i)_{cd} (U \tau^i U^\dagger)_{dc}$

$$\tau^i_{ab} R^{ij} \Pi^j = \frac{1}{2} * 2 (\delta_{ad} \delta_{bc} - \frac{1}{2} \delta_{ab} \delta_{cd}) (U \tau^i U^\dagger)_{dc} \Pi^j$$
$$= (U \tau^i \Pi^j U^\dagger)_{ab}$$

$$\left. \begin{array}{l} \text{Tr}(AB) = \text{Tr}(BA) \\ \text{Tr}(U^\dagger \tau^i U) = \text{Tr}(\tau^i U U^\dagger) \end{array} \right\}$$

$$\Pi = \vec{c} \cdot \vec{\pi} \rightarrow U \Pi U^\dagger = U (\vec{c} \cdot \vec{\pi}) U^\dagger$$

Invariants

$$\Psi \vec{c} \cdot \vec{\pi} \Psi \rightarrow (\Psi U^\dagger) (U \vec{c} \cdot \vec{\pi} U^\dagger) (U \Psi) = \Psi \vec{c} \cdot \vec{\pi} \Psi$$

adjoint $(\vec{c} \cdot \vec{v}) \rightarrow U (\vec{c} \cdot \vec{v}) U^\dagger$

Another invariant $\frac{1}{2} \text{Tr} (\vec{c} \cdot \vec{\pi} \vec{c} \cdot \vec{\pi}) = \frac{1}{2} \text{Tr} (\vec{c} \cdot \vec{v}) \vec{v} \cdot \vec{\pi} \vec{v} = \vec{v} \cdot \vec{v}$
 $\Rightarrow \frac{1}{2} \text{Tr} (U \vec{c} \cdot \vec{\pi} U^\dagger U \vec{c} \cdot \vec{\pi} U^\dagger) = \frac{1}{2} \text{Tr} (\vec{c} \cdot \vec{\pi} \vec{c} \cdot \vec{\pi})$

Calculations

$$\psi = \begin{pmatrix} \psi_p \\ \psi_n \end{pmatrix}$$

$$\vec{\tau} \cdot \vec{\pi} = \tau_3 \pi^3 + \frac{1}{2} \left[(\tau_1 + i\tau_2)(\pi_1 - i\pi_2) + (\tau_1 - i\tau_2)(\pi_1 + i\pi_2) \right]$$

$$\tau_{\pm} = \frac{1}{2} (\tau_1 \pm i\tau_2)$$

$$\pi^{\pm} = \frac{1}{\sqrt{2}} (\pi_1 \pm i\pi_2)$$

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$$\Rightarrow \vec{\tau} \cdot \vec{\pi} = \begin{pmatrix} \pi^3 & \sqrt{2}\pi^+ \\ \sqrt{2}\pi^- & -\pi^3 \end{pmatrix}$$

$$\pi \cdot \vec{\pi} = \pi^3 \pi^3 + 2\pi^+ \pi^-$$

$$\mathcal{L} = ig \bar{\psi} \vec{\tau} \cdot \vec{\pi} \gamma_5 \psi \xrightarrow{\text{drop } \gamma_5} ig (\bar{P}, \bar{N}) \begin{pmatrix} \pi^0 & \sqrt{2}\pi^+ \\ \sqrt{2}\pi^- & -\pi^0 \end{pmatrix} \begin{pmatrix} P \\ N \end{pmatrix}$$

$$= ig (\bar{P} P \pi^0 - \bar{N} N \pi^0) + \sqrt{2} g \bar{P} N \pi^+ + \sqrt{2} g \bar{N} P \pi^-$$

$$\text{Also } \mathcal{L} = -\frac{\lambda}{4} (\pi^i \pi^i)^2 = -\frac{\lambda}{4} (\pi^0{}^2 + 2\pi^+ \pi^-)^2 = -\frac{\lambda}{4} (\pi^0{}^4 + 4\pi^0{}^2 \pi^+ \pi^- + 4\pi^{+2} \pi^{-2})$$

$$\langle \pi^0 \pi^0 | \mathcal{L} | \pi^0 \pi^0 \rangle = -6\lambda$$

$$\begin{array}{c} \pi^0 \\ \nearrow \\ \pi^0 \\ \leftarrow \\ \pi^0 \end{array} = 6i\lambda$$

$$\langle \pi^0 \pi^- | \mathcal{L} | \pi^0 \pi^- \rangle = -\frac{\lambda}{4} \times 4 \times 2 = -2\lambda$$

$$\langle \pi^+ \pi^- | \mathcal{L} | \pi^+ \pi^- \rangle = -4\lambda$$

O(N) scalar theory

N real fields ϕ^i $i = 1 \dots N$

$\phi^i \phi^i$ O(N) invariant

$$\phi^i \rightarrow R^{ij} \phi^j$$

$$R^{ij} R^{ik} = \delta^{jk}$$

$$\mathcal{L} = \frac{1}{2} \partial_\mu \phi^i \partial^\mu \phi^i - V(\phi^i \phi^i)$$

$$V = \frac{1}{2} m^2 \phi^i \phi^i - \frac{\lambda}{4} (\phi^i \phi^i)^2$$

Linear σ Model

Gell Mann + Levy 1960

$$\psi = \begin{pmatrix} \psi_p \\ \psi_n \end{pmatrix}$$

$$(\sigma, \vec{\pi}^i) \sim (\pi^i, \pi^4) \rightarrow (\sigma^2 + \vec{\pi}^2) \quad O(4) \text{ invariant}$$

$$V(\sigma^2 + \vec{\pi}^2) = \frac{1}{2} \mu^2 (\sigma^2 + \vec{\pi}^2) - \frac{\lambda}{4} (\sigma^2 + \vec{\pi}^2)^2$$

$$\mathcal{L} = \bar{\psi} i \not{\partial} \psi - g \bar{\psi} (\sigma - i \vec{\tau} \cdot \vec{\pi} \gamma_5) \psi - V(\sigma^2 + \vec{\pi}^2)$$

\uparrow no mass term \uparrow \uparrow

Symmetry $SU(2)_L \otimes SU(2)_R$

$$\psi_L \rightarrow \psi'_L = L \psi_L$$

$$\psi_R \rightarrow \psi'_R = R \psi_R$$

$$L = e^{-i \vec{\alpha}_L \cdot \vec{\tau}}$$

$$R = e^{-i \vec{\alpha}_R \cdot \vec{\tau}}$$

$$(\sigma_{-i} \vec{c}_i \cdot \vec{\pi}) \rightarrow \sigma'_{-i} \vec{c}_i \cdot \vec{\pi} = L(\sigma_{-i} \vec{c}_i \cdot \vec{\pi}) \mathbb{R}^+$$

SU(N)

$$\psi = \begin{pmatrix} \psi_1 \\ \vdots \\ \psi_N \end{pmatrix}$$

with $\psi \rightarrow \psi' = U\psi$

$$U^\dagger U = 1 \\ \det U = 1$$

$$U = e^{-i\vec{\alpha} \cdot \vec{\lambda}} = e^{-i\alpha^i \lambda^i} \quad i = 1 \dots (N^2 - 1) \\ = e^{-i\alpha^A T^A}$$

$\lambda^i = 3 \times 3$ Traceless Hermitians

$$\text{Tr}(\lambda^i \lambda^j) = 2 \delta^{ij}$$

$$\lambda^i = \begin{pmatrix} \tau^i & 0 \\ 0 & 0 \end{pmatrix}$$

$$i = 1, 2, 3$$

✓

$$(\lambda^i)_{ab} (\lambda^j)_{cd} = 2 \left(\delta_{ad} \delta_{cb} - \frac{1}{N} \delta_{ab} \delta_{cd} \right)$$

Representations

$$\psi \Rightarrow U \psi$$

fundamental

N

$$\vec{\lambda} \cdot \vec{V} \rightarrow U \vec{\lambda} \cdot \vec{V} U^\dagger$$

adjoint

$N^2 - 1$

$$V^i \rightarrow R^{ij} V^j$$

$$\text{with } R^{ij} = \frac{1}{2} \text{Tr}(U \tau^i U^\dagger \tau^j)$$

Invariants

$$\bar{\psi} \vec{\lambda} \cdot \vec{V} \psi$$

$$V^i V^i = \frac{1}{2} \text{Tr}(\lambda \cdot V \lambda \cdot V)$$

$$I_3 = \frac{1}{2} \text{Tr}((\lambda \cdot V_1)(\lambda \cdot V_2)(\lambda \cdot V_3))$$