

Gauge Theory 1

9/24

Note Title

9/24/2009

Goals

- 1) Extend to YM
- 2) Teach right
- 3) Survey of major lessons

Nonabelian - Yang Mills

$$\begin{array}{l} \text{QED} \quad U(1) \\ \text{YM} \Rightarrow \text{SU}(N) \end{array}$$

Local

$$\psi \rightarrow U(x) \psi$$

$$\psi = \begin{pmatrix} \psi_1 \\ \vdots \\ \psi_N \end{pmatrix}$$

$$U = e^{-i \alpha^a T^a \cdot \frac{\Delta}{2}} \leftarrow *$$

To form invariant

$$\mathcal{L} = \bar{\psi} i \not{D} \psi \rightarrow \bar{\psi}' i \not{D}' \psi' = \bar{\psi} U^\dagger \not{D}' U \psi$$

$$\Rightarrow \not{D} \rightarrow \not{D}' = U \not{D} U^\dagger$$

$$\text{or } \not{D} \psi \rightarrow U (\not{D} \psi)$$

SU(N) gauge fields

$$\partial_\mu U \sim -i \partial_\mu \vec{A} \cdot \frac{\vec{\lambda}}{2}$$

$$D_\mu = \partial_\mu + ig A_\mu^i \frac{\lambda^i}{2}$$

Make it work:

$$D'_\mu = U \left[\partial_\mu + ig \frac{\vec{A} \cdot \vec{\lambda}}{2} \right] U^\dagger = \partial_\mu + ig \frac{\vec{A}' \cdot \vec{\lambda}}{2}$$

$$= \partial_\mu + U \partial_\mu U^\dagger + ig \underbrace{U \frac{\vec{A} \cdot \vec{\lambda}}{2} U^\dagger}_{\text{rotations}}$$

$$\frac{\vec{\lambda} \cdot \vec{A}'^2}{2} = U \frac{\vec{\lambda} \cdot \vec{A}^2}{2} U^\dagger - \frac{i}{g} U \partial_\mu U^\dagger \quad \leftarrow \text{Hermitian + Traceless}$$

Small transformations

$$U = \left(1 - i\alpha \cdot \frac{\vec{\lambda}}{2}\right)$$

$$\frac{\vec{\lambda}}{2} \cdot \vec{A}' = \left(1 - i\alpha \cdot \frac{\vec{\lambda}}{2}\right) \frac{\vec{\lambda}}{2} \cdot A_m \left(1 + i\alpha \cdot \frac{\vec{\lambda}}{2}\right) - \frac{i}{g} \partial \left(\frac{i\alpha \cdot \vec{\lambda}}{2}\right)$$

$$= \frac{\vec{\lambda} \cdot A_m}{2} + \frac{i}{4} \underbrace{[\vec{\lambda} \cdot A_m, \vec{\lambda} \cdot \alpha]} + \frac{1}{g} \partial_m \frac{\vec{\lambda} \cdot \alpha}{2}$$

Use $[\lambda^i, \lambda^j] = 2i f^{ijk} \lambda^k$

antisymmetric
 $- SU(N)$
 $SU(2) = \epsilon^{ijk}$

$$A_m^{\prime i} = A_m^i + \frac{1}{g} \partial_m \alpha^i + f^{ijk} A_m^k \alpha^j$$

$\underbrace{\quad}_{\text{gauge}} \quad \quad \quad \underbrace{\quad}_{\text{rotation}}$

$$A_m^{\prime i} = R^{ij} A_m^j - \frac{i}{g} \text{Tr}(\lambda^i U \partial_m U^\dagger)$$

$$R^{ij} = \frac{1}{2} \text{Tr}(U \lambda^i U^\dagger \lambda^j)$$

To show Hermitian & Traceless

1) Hermitian $(i U \partial_\mu U^\dagger)^\dagger = -i (\partial_\mu U) U^\dagger = +i U \partial_\mu U^\dagger$

$$\begin{aligned} U^\dagger U = 1 &\Rightarrow \partial_\mu (U^\dagger U) = 0 \Rightarrow (\partial_\mu U^\dagger) U = -U^\dagger \partial_\mu U \\ U U^\dagger = 1 &\Rightarrow (\partial_\mu U) U^\dagger = -U \partial_\mu U^\dagger \end{aligned}$$

2) Traceless - no elegant proof

$$\begin{aligned} U \partial_\mu U^\dagger &= \left(1 - i \alpha \frac{\lambda_{+--}}{2} + \dots \right) \partial_\mu \left(1 + i \alpha \frac{\lambda_{+--}}{2} + \dots \right) \\ &= \lambda^x + (i \alpha \lambda_{+--}) \end{aligned}$$

To get $F_{\mu\nu}^i$

$$[D_\mu, D_\nu] \rightarrow [U D_\mu U^\dagger, U D_\nu U^\dagger] = U [D_\mu, D_\nu] U^\dagger \\ \equiv ig \frac{\vec{\lambda}}{2} \cdot \vec{F}_{\mu\nu}$$

$$[D_\mu, D_\nu] = ig \left[\partial_\mu \frac{\vec{\lambda} \cdot \vec{A}_\nu}{2} - \partial_\nu \frac{\vec{\lambda} \cdot \vec{A}_\mu}{2} \right] + \left(\frac{ig}{2} \right)^2 \underbrace{[\vec{\lambda} \cdot \vec{A}_\mu, \vec{\lambda} \cdot \vec{A}_\nu]}_{2if^{ijk} \lambda^k A_\mu^i A_\nu^j}$$

Then

$$F_{\mu\nu}^i = \partial_\mu A_\nu^i - \partial_\nu A_\mu^i + g f^{ijk} A_\mu^j A_\nu^k$$

$$\vec{\lambda} \cdot \vec{F}_{\mu\nu} = \partial_\mu \vec{\lambda} \cdot \vec{A}_\nu - \partial_\nu \vec{\lambda} \cdot \vec{A}_\mu + \frac{g}{2} [\vec{A} \cdot \vec{A}, \vec{\lambda} \cdot \vec{A}]$$

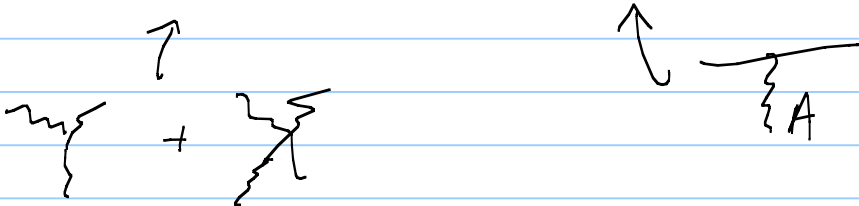
$$\vec{\lambda} \cdot \vec{F}_{\mu\nu} \rightarrow U \vec{\lambda} \cdot \vec{F}_{\mu\nu} U^\dagger$$

Invariant

$$\frac{1}{2} \text{Tr}(\vec{\lambda} \cdot \vec{F}_{\mu\nu} \vec{\lambda} \cdot \vec{F}^{\mu\nu}) \rightarrow \frac{1}{2} \text{Tr}(U \lambda \cdot F U^\dagger U \lambda \cdot F U^\dagger)$$

$$= F_{\mu\nu}^i F^{i\mu\nu}$$

Yang Mills Lagrangian

$$\mathcal{L} = -\frac{1}{4} F_{\mu\nu}^i F^{i\mu\nu} + \bar{\Psi} (\not{D} - m) \Psi$$


P. I. Quantization

1) The propagator does not exist

$$\square A_\mu - \partial_\mu \partial^\nu A_\nu = J_\mu$$

Like

$$(\square g^{\mu\nu} - \partial^\mu \partial^\nu) D_{F\mu\lambda}(x-x') = g^{\nu\lambda} \delta^4(x-x')$$

F.T.

$$(-k^2 g^{\mu\nu} + k^\mu k^\nu) G_{\mu\lambda}(k) = g^{\nu\lambda}$$

$$\uparrow a(k^2) g_{\mu\lambda} + b(k^2) k_\mu k_\lambda$$

$$\Rightarrow a(k^2) (-k^2 g^{\nu\lambda} + k^\nu k_\lambda) = g^{\nu\lambda} \quad \text{impossible}$$

$$(\Box g^{\mu\nu} - \partial^\mu \partial^\nu) \int \frac{d^4 k}{(2\pi)^4} G_{\mu\lambda}(k^2) e^{-ik \cdot (x-x')} = g^{\nu\lambda} \int \frac{d^4 k}{(2\pi)^4} e^{-ik \cdot (x-x')}$$

Why important?

$$Z[\mathcal{J}] = \int [d\phi] e^{i\mathcal{L}[\phi] + \mathcal{J}\phi} = \frac{1}{|\det \Theta|} e^{-\langle \mathcal{J} \Theta^{-1} \mathcal{J} \rangle}$$

with QED \Rightarrow no inverse, blows up

Diagnosis $\int dA_\mu$

- ∞ # of gauge copies in PI
- doesn't factor here

Simple example of method

2 d integral

$$Z = \int dx dy e^{iS(x,y)}$$

$$\checkmark (x, y) \Rightarrow (r, \phi)$$

with symmetry, $S(x, y) = S(r)$
 ϕ does not appear

Fancy method

$$1 = \int d\theta \delta(\theta - \phi)$$

$$Z = \int r dr d\phi \int d\theta \delta(\theta - \phi) e^{iS(r)} = \int d\theta \underbrace{\int dr \delta(\theta - \phi)}_{Z_0} e^{iS}$$

$$= \int d\theta Z_0 = 2\pi Z_0$$

\uparrow
 Z_0 independent of θ

More realistic

$$q(r) = 0$$

if $r_0 = (r, \phi + \theta)$

$$1 = \int d\theta \left(\frac{\partial q}{\partial \theta} \right)_{q=0} \delta(q(r_0))$$

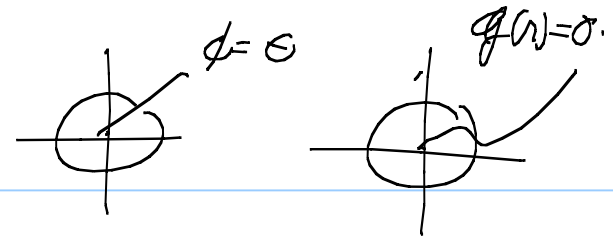
$$\int d\theta \delta(q(r_0)) = \frac{1}{\left| \frac{\partial q}{\partial \theta} \right|_{q=0}}$$

$$Z = \int d^2 r \left[\int d\theta \left(\frac{\partial q}{\partial \theta} \right) \delta(q(r_0)) \right] e^{iS(r)}$$

$$= \int d\theta Z_\theta = 2\pi Z_0$$

$$\text{with } Z_\theta = \int d^2 r \left(\frac{\partial q}{\partial \theta} \right) \delta(q(r_0)) e^{iS(r)}$$

↑ ↑



Gauge Theory version

$$f(A_\mu) = 0 \quad \leftarrow \text{at each point in space time}$$

Identity

$$\text{Gauge trans } A_\mu \rightarrow A_\mu^\theta = A_\mu + \partial_\mu \theta$$

$$1 = \int [d\theta(x)] \Delta(A) \delta(f(A_\mu^\theta))$$

$$\text{where } \Delta(A) = \text{vdet} \left(\frac{\partial f}{\partial \theta} \right) \Big|_{f=0}$$

$$\text{example } f(A_\mu) = \partial_\mu A^\mu$$

This does factor out the gauge copies

$$Z = \int [dA][d\theta] \Delta(A) \delta(F(A^\theta)) e^{i \int d^4x \mathcal{L}}$$

if $\Delta(A)$ independent of θ (norm) \leftarrow

\Rightarrow factor out $[d\theta]$ (gauge trans)

$\int d\theta = N \Rightarrow$ only constrained A_μ in P_T

$$Z_f[P_T] = N \int [dA] \Delta(A) \delta(F(A)) e^{i \int d^4x (\mathcal{L} + J_\mu A^\mu)}$$

\Rightarrow get inverse

Check that $\Delta(A)$ is gauge invariant

$$\int [d\theta] \delta(f(A^\theta)) = \Delta^{-1}(A)$$

$$\begin{aligned}\Delta^{-1}(A^{\theta_0}) &= \int [d\theta] \delta(f(A^{\theta_0})) \\ &= \int [d\theta'] \delta(f(A^{\theta'})) \\ &= \Delta^{-1}(A)\end{aligned}$$

$$\begin{aligned}\text{let } \theta_0 &= \theta' \\ [d\theta] &= [d\theta']\end{aligned}$$