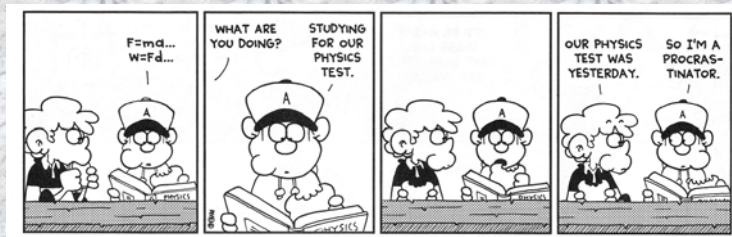


Announcements 3 Apr 09

- Exam 2

- Tue April 7 from 7 to 9 pm
- Make-up exams need to be arranged now
- Help session on Mon April 6 from 5 to 7 pm in HAS 20
- SI session on Mon April 6 from 7:15 to 8:30 pm (as usual)



1

Exam #2 Information (I)

- What will be covered?

- Motion in two dimensions (Chapter 3 Secs. 1-4, 6-7)
- Forces and Newton's Laws (Chapter 4 Secs. 1-8 and Chapter 5 Secs. 1-5)
- Gravity (Chapter 6 Sec. 6)
- Torque, center of gravity and static equilibrium (Chapter 7 Secs. 2-3 and Chapter 8 Sec. 1-2)
- Material from homework assignments #4, #5, #6, #7, #8

- Exam format

- Multiple choice problems + 1 written problem
- Mixture of conceptual questions (PRS like) and numerical problems (homework like)
- Sample exam + MasteringPhysics practice now available (sample exam will be discussed during the special help session)

Exam #2 Information (II)

- Exam location on Tuesday April 7 from 7 to 9 pm
 - Location depends on the first letter of your last name:
 - A through C HAS 124
 - D through H HAS 126
 - I through R MORRILL 1N329
 - S through Z HAS 134
- What to take to the exam?
 - Bring calculator, #2 pencil + *hand-written* formula sheet (1 sheet) + student ID
 - No scratch paper (should not be needed)
- Resources
 - Help session on Monday April 6 from 5 to 7 pm in HAS 20
 - Sample exam 2 + homework + lecture notes + textbook problems (answers to odd-numbered problems in the back of the book)

S.Willocq

Physics 131

3

Exam 2: units

Use SI units

distance unit:	m
mass unit:	kg
time unit:	s
force unit:	N (or kg m/s ²)

Conversions

1 km	=	10 ³ m
1 cm	=	10 ⁻² m
1 mi	=	1600 m
1 gram	=	10 ⁻³ kg
1 h	=	3600 s
1 min	=	60 s
1 lb	=	4.45 N

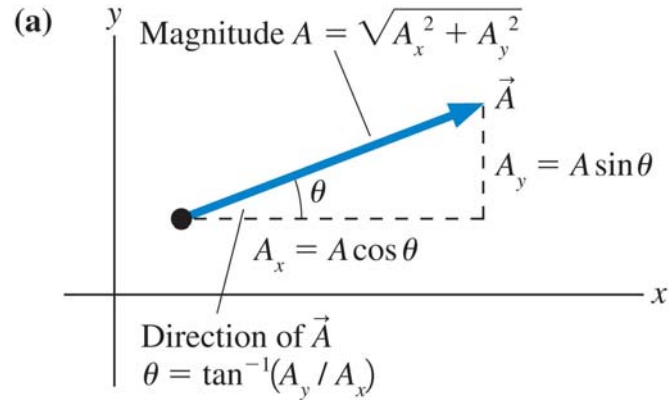
S.Willocq

Physics 131

4

Exam 2: vectors & concepts

Work with x- and y-components, and angle θ



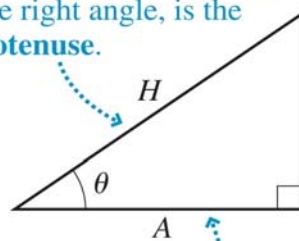
Know and understand main concepts in the lecture notes

acceleration, forces, Newton's laws, projectile motion, gravity, torque, static equilibrium

Trigonometry reminder: “SOHCAHTOA”

$$\sin \theta = \frac{O}{H}$$
$$\cos \theta = \frac{A}{H}$$
$$\tan \theta = \frac{O}{A}$$

The longest side, opposite to the right angle, is the **hypotenuse**.



This is the side **opposite** to the angle.

This is the side **adjacent** to the angle.

To determine the x- and y-axis components of a vector it is useful to remember “SOH CAH TOA”

For example, the x-axis component would be $A = H \cos \theta$

Exam 2: Equation toolkit

Motion kinematics

valid only if constant acceleration
btw initial time t_i and final time t_f

$$(v_x)_f = (v_x)_i + a_x \Delta t$$

$$(v_x)_f^2 = (v_x)_i^2 + 2a_x \Delta x$$

$$x_f = x_i + (v_x)_i \Delta t + \frac{1}{2} a_x (\Delta t)^2$$

Projectile 2D motion $a_x = 0$ and $a_y = -g$

$$(v_x)_f = (v_x)_i$$

$$x_f = x_i + (v_x)_i \Delta t$$

$$(v_y)_f = (v_y)_i - g \Delta t$$

$$(v_y)_f^2 = (v_y)_i^2 - 2g \Delta y$$

$$y_f = y_i + (v_y)_i \Delta t - \frac{1}{2} g (\Delta t)^2$$

Compute Δt to relate motion along x-axis to motion along y-axis
If Δy is given, generally compute Δt from y-motion
If Δx is given, generally compute Δt from x-motion

Exam 2: Equation toolkit

Forces and motion

acceleration is the link between
forces and motion

Newton's 2nd law

$$\sum F_x = ma_x$$

$$\sum F_y = ma_y$$

If given forces acting on an object:

1. Identify forces & draw free-body diagram
2. Compute net force along x and y axes (or just 1 axis as required)
3. Compute corresponding **acceleration** using Newton's 2nd law
4. Use kinematics equations (previous slide) to determine the change in motion (e.g. find final position, velocity, etc.)

If given information about motion (e.g. displacement Δx , time interval Δt , initial and/or final velocities):

1. Use kinematics equations and motion information to compute the **acceleration**
2. Compute magnitude and direction of net force using Newton's 2nd law

Exam 2: Equation toolkit

Different forces

1. **Tension** T directed along a string or rope
2. **Weight** $w = m g$
Apparent weight $w_{app} = m g + m a$
3. **Normal force** n perpendicular to surface of two objects in contact
 ($n = m g$ not true in general, true only in special cases)
4. **Friction** static $f_s \max = \mu_s n$
 kinetic $f_k = \mu_k n$
5. **Gravitational force** $F_{lon2} = G \frac{m_1 m_2}{r^2}$

Weight for object of mass m is $w_{planet} = m g_{planet}$ with $g_{planet} = G \cdot \frac{M_{planet}}{(R_{planet})^2}$

G is a true constant

$-g = -9.8 \text{ m/s}^2$ is the free-fall acceleration due to gravity on the surface of the earth, not the correct value elsewhere

Exam 2: Equation toolkit

Torque

$$\tau = r_{\perp} F = r F \sin \phi$$

Center of gravity

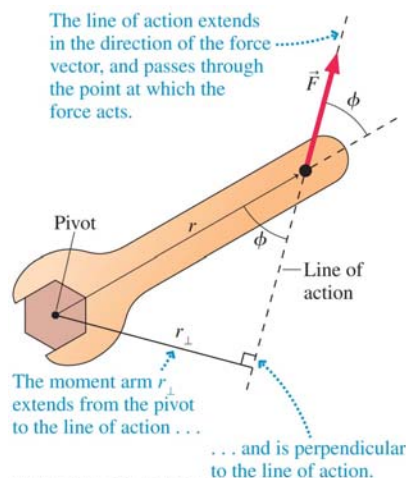
The x -coordinate of the center of gravity is

$$x_{cg} = \frac{x_1 m_1 + x_2 m_2 + x_3 m_3 + \dots}{m_1 + m_2 + m_3 + \dots}$$

Static equilibrium

$$\left. \begin{array}{l} \sum F_x = 0 \\ \sum F_y = 0 \end{array} \right\} \text{No net force}$$

$$\left. \begin{array}{l} \sum \tau = 0 \end{array} \right\} \text{No net torque}$$



For an extended object (e.g. horizontal beam in problem 7.20), consider the weight of the beam as acting at its center of gravity

Choose pivot point at a location where one of the forces is unknown